Code No: D6303 JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY HYDERABAD M.TECH II - SEMESTER EXAMINATIONS, APRIL/MAY 2012 ROBOTICS AND MACHINE VISION (IMAGE PROCESSING)

Time: 3hours

## Answer any five questions All questions carry equal marks

Max. Marks: 60

- 1.a) Explain the robot anatomy and the characteristics of human arm.
- b) What are homogeneous transformation matrices? Discuss their significance with suitable examples.
- 2.a) Explain the Demerit Huntenburg notation and the euler angles.
- b) Explain about jacobian inverse and jacobian singularities and bring out their significance in Robotics.
- 3. Explain about open and closed loop control and force control strategies.
- 4. Explain the Canny edge detection technique and Shen Castan edge detection techniques with suitable examples and compare.
- 5.a) State and explain various areas of applications of edge detection.
- b) What is meant by gray scale image, binary image and color image? Give suitable examples and compare their features.
- 6.a) What is meant by gray level segmentation? Discuss the relaxation methods for it?
  - b) What is a skeleton? Discuss about medial axis transform.
- 7.a) What is meant by thinning? Explain the force based thinning method.
- b) State and explain various 2D Wavelets.
- 8. Write short notes on the followinga) OCRb) RPY representationc) Symbol Recognition

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